



High price-performance ratio

VFC3-021-0.2K ~2.2K  
VFC3-023-0.2K ~3.7K  
VFC3-043-0.4K ~5.5K

Thank you for choosing Sitronic inverters VFC3 series.

This instruction will explain the use and precautions of the product. Please read this instruction carefully before installation and use the inverter correctly and safely.

1) Safety Instructions

**Safety Instructions**

- ☑ The qualified specialized person should be invited to install, operate, maintain and inspect the product.
- ☑ In the instruction, the levels of the safety caution include "Warning" and "Caution".
- ⚠ **Warning: the incorrect operation may cause hazardous situation, and accordingly lead to death or serious injury.**
- ⚠ **Caution: the incorrect operation may cause hazardous situation, and accordingly lead to general or minor injury or damage of the object.**

**Warning**

- ✓ The front cover plate and the wiring board should not be opened when the inverter is powered on. In addition, the inverter should not be operated when the front cover plate and the wiring board are demounted. Otherwise, the electric shock may be caused due to contacting with the high-voltage terminal and the charging part.
- ✓ If the wiring needs to be changed or inspection is required, the power supply of the inverter should be turned off first. There is still high voltage inside the inverter before the LED display of the inverter is turned off. Therefore, please don't touch the internal circuit and parts.
- ✓ The inverter must be earthed correctly.
- ✓ Please don't operate with wet hands, don't touch the heat sink, and don't plug and unplug the cable; or electric shock may be caused.
- ✓ Do not replace the cooling fan when the inverter is powered on, otherwise the risk may occur. It is dangerous to replace the cooling fan when the inverter is powered on.

**Caution**

- ✓ Voltage applied to each terminal must be the one specified in the user manual; otherwise, failure or damage may be caused.
- ✓ Do not operate a voltage-resistant test for the parts inside the inverter because semiconductors in inverter may be easily damaged due to high-voltage breakdown.
- ✓ Do not touch the inverter because the temperature of the inverter is very high when it is powered on or right after disconnecting the power supply, only built-in keypad is touchable, otherwise, burn may occur.
- ✓ Failure or damage may be caused due to wrong wiring.
- ✓ Do not reverse the polarities (+, -) by mistake, failure or damage may be caused.
- ✓ Please install the inverter on nonflammable walls without holes (to avoid contacts with the cooling fin of the inverter from the back). If the inverter is installed on or close to flammable objects it may cause a fire.
- ✓ Please disconnect the inverter from power supply in case of failure. Overload current passes through the inverter continuously may cause a fire.

2) Product Model

VFC3-043-0.75K-xy

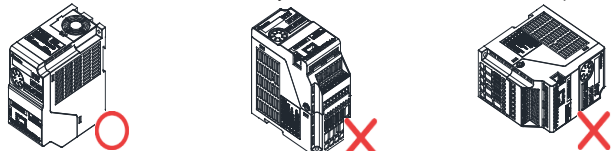
| Series category | Voltage level  | Capacity | Others   |
|-----------------|--|----------|--|
| VFC3 series     | -043 : three phase 440V<br>-023 : three phase 220V<br>-021 : single phase 220V | 0.75kW   | None : General model<br>-xy : Customize or specialize or region difference |

3) Installation Environment

|                         |   |
|-------------------------|---|
| Ambient temperature     | -10 ~ +50°C (non-freezing), parallel install -10~ +40°C (non-freezing).                           |
| Ambient humidity        | Under 90%Rh (non-condensing).   |
| Storage temperature     | -20 ~ +65°C.  |
| Surrounding environment | Indoor, no corrosive gas, no flammable gas, no flammable powder.                                  |
| Altitude                | Altitude below 2000 meters, when altitude is above 1,000 m, derate the rated current 2% per 100 m |
| Vibration               | Below 5.9m/ s <sup>2</sup> (0.6G)   |
| Grade of protection     | IP20  |
| The degree of pollution | 2   |

4) Installation and Wiring

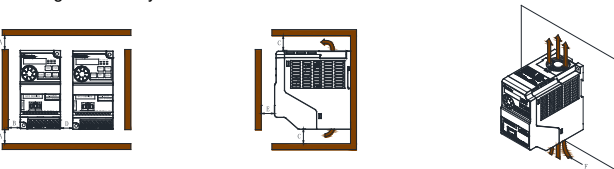
▶ Please install the inverter vertically in order not to reduce the heat dissipation effect:



(a) Vertical arrangement (b) Horizontal arrangement (c) Level arrangement

▶ Please follow the installation restrictions shown below to ensure enough ventilation space for inverter cooling and wiring space:

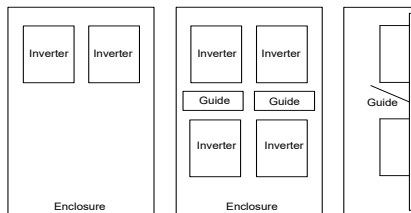
- Single or side by side installation :



unit : mm

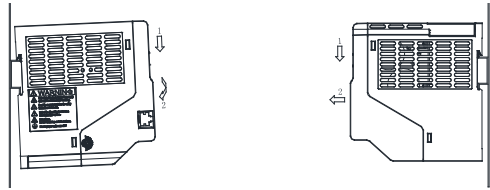
| size | Frame A               | Frame B |
|------|-----------------------|---------|
| A    | 50                    | 50      |
| B    | 50                    | 50      |
| C    | 100                   | 100     |
| D    | 50                    | 50      |
| E    | 50                    | 50      |
| F    | ventilation direction |         |

- Arrangement of multiple inverters :



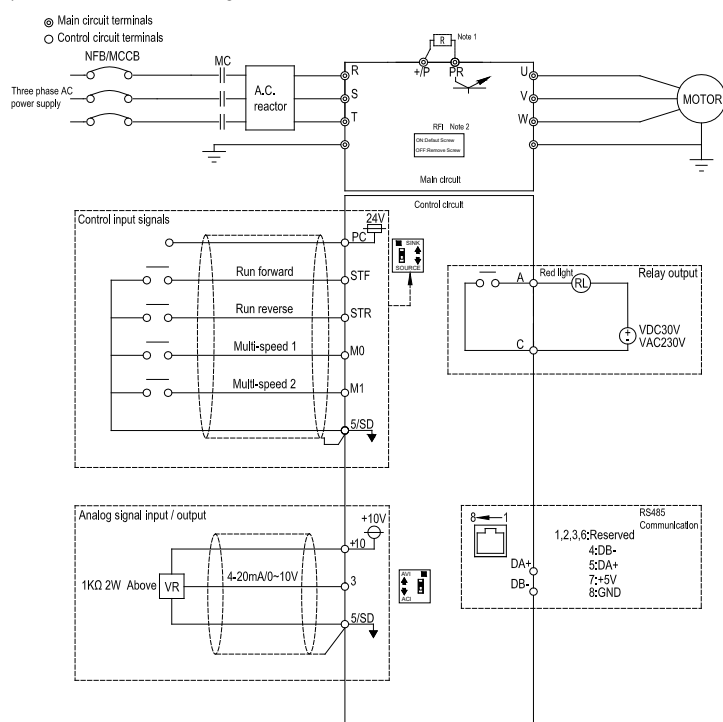
(a) Horizontal arrangement (b) Vertical arrangement

- Din rail installation :



(a) DIN rail mounting (b) DIN rail remove

5) Terminal Connection Diagrams



Note 1: VFC3-043-0.4K~1.5K, VFC3-023-0.2~1.5K, VFC3-021-0.2~0.75K without +/P and PR terminals.

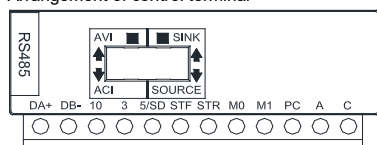
Note 2: All VFC3 have built-in RFI filters to suppress electromagnetic interference, but to comply with CE regulations, please refer to the relevant instructions in the instruction manual for installation.

6) Main Circuit Wiring and Terminal Specification

| Inverter model | Terminal screw specifications | Tightening torque(Kgf.cm) | Recommended wiring specification(mm <sup>2</sup> ) |         |         |                 | Recommended wiring specification (AWG) |         |         |                 |
|----------------|-------------------------------|---------------------------|--|---------|---------|-----------------|--|---------|---------|-----------------|
|                |                               |                           | R, S, T  | U, V, W | +/P, PR | Grounding Cable | R, S, T                                | U, V, W | +/P, PR | Grounding Cable |
| VFC3-021-0.2K  | M3                            | 4-6                       | 2.5  | 1.5     | ---     | 1.5             | 14                                     | 16      | ---     | 16              |
| VFC3-023-0.2K  |                               |                           | 1.5  | 1.5     | ---     | 1.5             | 16                                     | 16      | ---     | 16              |
| VFC3-043-0.4K  |                               |                           | 1.5  | 1.5     | ---     | 1.5             | 16                                     | 16      | ---     | 16              |
| VFC3-021-0.4K  |                               |                           | 2.5  | 2.5     | ---     | 2.5             | 14                                     | 14      | ---     | 14              |
| VFC3-023-0.4K  |                               |                           | 2.5  | 2.5     | ---     | 2.5             | 14                                     | 14      | ---     | 14              |
| VFC3-043-0.75K |                               |                           | 2.5  | 2.5     | ---     | 2.5             | 14                                     | 14      | ---     | 14              |
| VFC3-021-0.75K |                               |                           | 2.5  | 2.5     | ---     | 2.5             | 14                                     | 14      | ---     | 14              |
| VFC3-023-0.75K |                               |                           | 2.5  | 2.5     | ---     | 2.5             | 14                                     | 14      | ---     | 14              |
| VFC3-043-1.5K  |                               |                           | 2.5  | 2.5     | ---     | 2.5             | 14                                     | 14      | ---     | 14              |
| VFC3-023-1.5K  |                               |                           | 2.5  | 2.5     | ---     | 2.5             | 14                                     | 14      | ---     | 14              |
| VFC3-021-1.5K  |                               |                           | 2.5  | 2.5     | 2.5     | 2.5             | 14                                     | 14      | 14      | 14              |
| VFC3-043-2.2K  |                               |                           | 2.5  | 2.5     | 2.5     | 2.5             | 14                                     | 14      | 14      | 14              |
| VFC3-023-2.2K  |                               |                           | 4  | 4       | 4       | 4               | 12                                     | 12      | 12      | 12              |
| VFC3-021-2.2K  |                               |                           | 4  | 4       | 4       | 4               | 12                                     | 12      | 12      | 12              |
| VFC3-023-2.2K  |                               |                           | 4  | 4       | 4       | 4               | 12                                     | 12      | 12      | 12              |
| VFC3-043-3.7K  |                               |                           | 2.5  | 2.5     | 2.5     | 2.5             | 10                                     | 14      | 14      | 14              |
| VFC3-043-5.5K  |                               |                           | 2.5  | 2.5     | 2.5     | 2.5             | 14                                     | 14      | 14      | 14              |
| VFC3-023-3.7K  |                               |                           | 4  | 4       | 4       | 4               | 12                                     | 12      | 12      | 12              |

7) Control Terminal

▶ Arrangement of control terminal



▶ Control terminal description

| Terminal type       | Terminal name | Function instructions   | Terminal specifications  |
|---------------------|---------------|---|--|
| Switch signal input | STF           | These four terminals are multifunction digital input, can switch between SINK/SOURCE. | Input impedance:4.7 kΩ<br>Action current:5mA(when 24VDC)<br>Voltage range:10~28VDC<br>Maximum frequency:1kHz |
|                     | STR           |   |  |
|                     | M0            |   |  |
|                     | M1            |   |  |
| Analog signal input | 10            | +10.5±0.5V  | Maximum current:10mA   |
|                     | 3             | 0~10V/4~20mA  | Input impedance:10kΩ   |

| Relay output           | A    | Multi-function relay output terminals. A-C is normally open contact, C is common terminal. | Maximum voltage:30VDC or 250VAC<br>Maximum current: Resistor load 5A NO/3A NC<br>Inductance load 2A NO/1.2A (cosΦ=0.4) |
|------------------------|------|--|--|
|                        | C    |  |  |
| Communication terminal | RJ45 | RS485, optical coupling isolation  | Distance: up to 500m   |
|                        | DA+  | RJ45 and "DA+/DB-" can't work at the same time   | Bit rate: up to 115200bps  |
|                        | DB-  |  |  |
| Common terminal        | 5/SD | Common terminal for terminal STF,STR,M0, M1,3 (SINK)                                       | ---  |
|                        | PC   | Common terminal for terminal STF,STR,M0, M1 (SOURCE)                                       | ---  |

Note1: When connecting control terminal to external devices, please pay attention to the voltage and current specifications of terminals to avoid damaging the inverter.

Note2 : The function of the control terminal is decided by inverter parameters, please refer to Instruction Manual for setting.

Note3 : Please pay attention to polarity when connect to external power and devices.

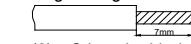
▶ Wiring method

• Wire connection

For the control circuit wiring, strip off the sheath of a cable, and use it with a blade terminal. For a single wire, strip off the sheath of the wire and apply directly.

Insert the blade terminal or the single wire into a socket of the terminal.

(1) Strip off the sheath for the below length. If the length of the sheath peeled is too long, a short circuit may occur with neighboring wires. If the length is too short, wires might come off.



(2) Crimp the blade terminal

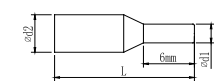
Insert wires to a blade terminal, and check that the wires come out for about 0 to 0.5 mm from a sleeve.

Check the condition of the blade terminal after crimping. Do not use a blade terminal of which the crimping is inappropriate, or the face is damaged.



• Please do use blade terminals with insulation sleeve. Blade terminals commercially available:

| Cable gauge (mm <sup>2</sup> ) | Blade terminals model | L (mm) | d1 (mm) | d2 (mm) | Manufacturer              | Tool type  |
|--------------------------------|-----------------------|--------|---------|---------|---------------------------|------------|
| 0.3                            | AI 0,25-6 WH          | 10.5   | 0.8     | 2       | Phoenix Contact Co., Ltd. | CRIMPFOX 6 |
| 0.5                            | AI 0,5-6 WH           | 12     | 1.1     | 2.5     |                           |            |
| 0.75                           | AI 0,75-6 GY          | 12     | 1.3     | 2.8     |                           |            |
| 0.75 (for two wires)           | AI-TWIN 2x0,75-6 GY   | 12     | 1.3     | 2.8     |                           |            |



Note1: Please Use a small flathead screw driver (tip thickness: 0.6mm, width:3.0mm). If a flathead screwdriver with a narrow tip is used, terminal block maybe damaged.

Note2: Tightening torque is 3.2~4.8kgf.cm, too large tightening torque can cause crew slippage, too little tightening torque can cause a short circuit or malfunction.

▶ Wiring Precautions

- After wiring, wire offcuts must not be left in the inverter.

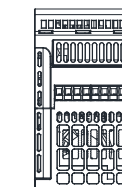
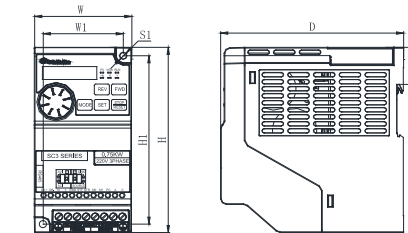
Wire offcuts can cause an alarm, failure or malfunction. Always keep the inverter clean. When drilling mounting holes in an enclosure etc., please make sure no metal scraps enter the inverter.

- To prevent a malfunction due to noise, keep the signal cables 10 cm (3.94 inches) or more away from the power cables, and keep it away from the input/output side.

- Set the voltage/current input switch correctly. Incorrect setting may cause a fault, failure or malfunction.

8) Appearance and Dimensions

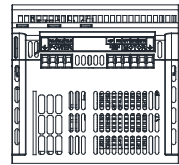
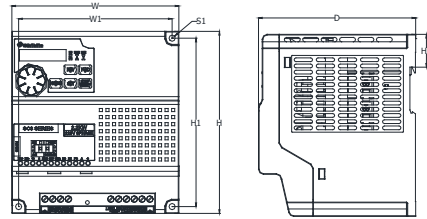
▶ Frame A



unit: mm

| Model          | W  | W1 | H   | H1  | H2   | D   | S1                             |
|----------------|----|----|-----|-----|------|-----|--------------------------------|
| VFC3-021-0.2K  | 68 | 56 | 132 | 120 | 26.5 | 128 | 5 (tighten torque 20~25kgf.cm) |
| VFC3-021-0.4K  |    |    |     |     |      |     |                                |
| VFC3-021-0.75K |    |    |     |     |      |     |                                |
| VFC3-023-0.2K  |    |    |     |     |      |     |                                |
| VFC3-023-0.4K  |    |    |     |     |      |     |                                |
| VFC3-023-0.75K |    |    |     |     |      |     |                                |
| VFC3-023-1.5K  |    |    |     |     |      |     |                                |
| VFC3-043-0.4K  |    |    |     |     |      |     |                                |
| VFC3-043-0.75K |    |    |     |     |      |     |                                |
| VFC3-043-1.5K  |    |    |     |     |      |     |                                |

► Frame B



| Model         | W   | W1  | H   | H1  | H2   | D   | S1                                   |
|---------------|-----|-----|-----|-----|------|-----|--------------------------------------|
| VFC3-021-1.5K | 136 | 125 | 147 | 136 | 26.5 | 128 | 5<br>(tighten torque<br>20~25kgf.cm) |
| VFC3-021-2.2K |     |     |     |     |      |     |                                      |
| VFC3-023-2.2K |     |     |     |     |      |     |                                      |
| VFC3-023-3.7K |     |     |     |     |      |     |                                      |
| VFC3-043-2.2K |     |     |     |     |      |     |                                      |
| VFC3-043-3.7K |     |     |     |     |      |     |                                      |
| VFC3-043-5.5K |     |     |     |     |      |     |                                      |

unit : mm

9) Optional Equipment

| Category | Name  | Description | Order code |
|----------|-------|-------------|------------|
| Keypad   | PU301 | LED display | SNKPU301   |
|          | DU06  | LED display | SNKDU06    |
|          | DU08  | LED display | SNKDU08    |
|          | PU302 | LED display | SNKPU302   |
|          | DU10  | LED display | SNKDU10    |

10) Parameter group

► System Parameter Group 00

| Group | No.           | Name                                     | Setting Range  | Default | User Setting |       |                    |         |   |  |
|-------|---------------|--|--|---------|--------------|-------|--------------------|---------|---|--|
| 00-00 | P.90          | Inverter model                           | Read only  | ---     |              |       |                    |         |   |  |
| 00-01 | P.188         | Firmware version                         | Read only  | ---     |              |       |                    |         |   |  |
| 00-02 | P.996 ~ P.999 | Parameter restoration                    | 0: Off   | 0       |              |       |                    |         |   |  |
|       |               |  | 1: Clear alarm history (P.996=1)   |         |              |       |                    |         |   |  |
|       |               |  | 2: Reset inverter (P.997=1)  |         |              |       |                    |         |   |  |
|       |               |  | 3: Restore all parameters to default (P.998=1)   |         |              |       |                    |         |   |  |
|       |               |  | 4: Restore some parameters to default 1 (P.999=1)  |         |              |       |                    |         |   |  |
|       |               |  | 5: Restore some parameters to default 2 (P.999=2)  |         |              |       |                    |         |   |  |
| 00-03 | P.77          | Selection of parameters write protection | 0: Parameters can be written only when the motor stops.  | 0       |              |       |                    |         |   |  |
|       |               |  | 1: Parameters cannot be written.   |         |              |       |                    |         |   |  |
|       |               |  | 2: Parameters can also be written when the motor is running.   |         |              |       |                    |         |   |  |
|       |               |  | 3: Parameters cannot be read when in password protection.  |         |              |       |                    |         |   |  |
|       |               |  | 00-04  |         |              | P.294 | Password parameter | 0~65535 | 0 |  |
|       |               |  | 00-05  |         |              | P.295 | Password setup     | 2~65535 | 0 |  |
| 00-06 | P.110         | Built-in keypad monitor selection        | X0: When inverter starts, built-in keypad enters monitor mode automatically, screen displays output frequency (with slip compensation).  | 2       |              |       |                    |         |   |  |
|       |               |  | X1: When inverter starts, built-in keypad displays target frequency.   |         |              |       |                    |         |   |  |
|       |               |  | X2: When inverter starts, built-in keypad enters monitor mode automatically, screen displays steady state output frequency.  |         |              |       |                    |         |   |  |
|       |               |  | X3: When inverter starts, built-in keypad enters monitor mode automatically, screen displays current pressure and feedback pressure of the constant pressure system in percentage. |         |              |       |                    |         |   |  |
|       |               |  | X4: When inverter starts, built-in keypad doesn't enter monitor mode but enter the previous mode before power off.   |         |              |       |                    |         |   |  |
|       |               |  | X5: When inverter starts, built-in keypad enters monitor mode automatically, screen displays current pressure and feedback pressure of the constant pressure system.               |         |              |       |                    |         |   |  |
| 00-07 | P.161         | Multi-function display                   | 0: Output AC voltage (V)   | 0       |              |       |                    |         |   |  |
|       |               |  | 1: DC bus voltage (V)  |         |              |       |                    |         |   |  |
|       |               |  | 2: Inverter temperature rising accumulation rate (%)   |         |              |       |                    |         |   |  |
|       |               |  | 3: Target pressure of the constant pressure system (%)   |         |              |       |                    |         |   |  |
|       |               |  | 4: Feedback pressure of the constant pressure system (%)   |         |              |       |                    |         |   |  |
|       |               |  | 5: Running frequency (Hz)  |         |              |       |                    |         |   |  |
|       |               |  | 6: Electronic thermal accumulation rate (%)  |         |              |       |                    |         |   |  |
|       |               |  | 7: Reserved  |         |              |       |                    |         |   |  |
|       |               |  | 8: Signal value (mA) of 3-5 input terminals (mA/V)   |         |              |       |                    |         |   |  |
|       |               |  | 9: Output power (kW)   |         |              |       |                    |         |   |  |
|       |               |  | 10: Reserved   |         |              |       |                    |         |   |  |
| 00-07 | P.161         | Multi-function display                   | 11: Forward reverse rotation signal.   | 0       |              |       |                    |         |   |  |
|       |               |  | Built-in keypad: Frd is forward, rEv is reverse, STOP is not operating status.   |         |              |       |                    |         |   |  |
|       |               |  | External keypad: 1 is forward, 2 is reverse, 0 is not operating status.  |         |              |       |                    |         |   |  |
|       |               |  | 12: NTC temperature (°C)   |         |              |       |                    |         |   |  |
|       |               |  | 13: Motor electronic thermal accumulation rate (%)   |         |              |       |                    |         |   |  |
|       |               |  | 14~18: Reserved  |         |              |       |                    |         |   |  |
| 00-08 | P.37          | Speed display                            | 0: Display output frequency(not mechanical speed)  | 0.0     |              |       |                    |         |   |  |
|       |               |  | 0.1~5000.0   |         |              |       |                    |         |   |  |
| 00-09 | P.259         | Speed display unit selection             | X0: Speed display unit is 1  | 1       |              |       |                    |         |   |  |
|       |               |  | X1: Speed display unit is 0.1  |         |              |       |                    |         |   |  |

|   |       |  |  |       |  |
|---|-------|--|--|-------|--|
| 00-10   | P.59  | Built-in keypad set target frequency selection | XXX0: Use wheel on built-in keypad or external keypad to set frequency               | ---   |  |
|   |       |  | XXX1: Use keypad knob on external keypad to set frequency                            |       |  |
|   |       |  | X0XX: After changing the frequency, it will be automatically stored within 30s       |       |  |
|   |       |  | X1XX: After changing the frequency, it will be automatically saved within 10s        |       |  |
|   |       |  | X2XX: Every frequency change will not save   |       |  |
|   |       |  | 0XXX: Set frequency will work immediately when use wheel on built-in keypad          |       |  |
| 1XXX: Set frequency will work after pressing SET when use up down button on built-in keypad |       |  |  |       |  |
| 00-11   | P.72  | Carrier frequency                              | 1~15kHz  | 5 kHz |  |
| 00-12   | P.31  | Soft-PWM carrier function selection            | 0: Off   | 0     |  |
|   |       |  | 1: When 00-11(P.72)<5, Soft-PWM is on(only apply to V/F control)                     |       |  |
| 00-13   | P.71  | Idling brake / DC brake                        | 0: Idling brake  | 1     |  |
|   |       |  | 1: DC brake  |       |  |
| 00-14   | P.75  | Stop function selection                        | 0: Press STOP button and inverter stop running in PU and H2 mode                     | 1     |  |
| 00-15   | P.78  | Prevent forward/reverse rotation selection     | 0: Forward/reverse rotation are both permitted.                                      | 0     |  |
|   |       |  | 1: Prevent reverse rotation (Giving reverse signal decelerates and stops the motor). |       |  |
| 00-16   | P.79  | Operation mode selection                       | 0: "PU mode", "external mode" and "Jog mode" are interchangeable.                    | 0     |  |
|   |       |  | 1: "PU mode" and "JOG mode" are interchangeable.                                     |       |  |
|   |       |  | 2: "External mode" only  |       |  |
|   |       |  | 3: "Communication mode" only   |       |  |
|   |       |  | 4: "Combined mode 1"   |       |  |
|   |       |  | 5: "Combined mode 2"   |       |  |
|   |       |  | 6: "Combined mode 3"   |       |  |
|   |       |  | 7: "Combined mode 4"   |       |  |
|   |       |  | 8: "Combined mode 5"   |       |  |
| 00-17   | P.97  | Second target frequency selection              | 0: Frequency set by built-in keypad  | 0     |  |
|   |       |  | 1: Frequency set by RS485 communication  |       |  |
|   |       |  | 2: Frequency set by analog input   |       |  |
| 00-19   | P.35  | Communication mode selection                   | 0: In communication mode, run signal and frequency is given by communication.        | 0     |  |
|   |       |  | 1: In communication mode, run signal and frequency is given by external signal.      |       |  |
| 00-21   | P.300 | Motor control mode selection                   | 0: Induction motor V/F control   | 0     |  |
|   |       |  | 1: Reserved  |       |  |
|   |       |  | 2: Induction motor simple vector control   |       |  |
| 00-24   | P.189 | 50Hz/60Hz switch selection                     | 0: Frequency related parameter default value is 60Hz                                 | 0     |  |
|   |       |  | 1: Frequency related parameter default value is 50Hz                                 |       |  |
| 00-25   | P.990 | Parameter display mode setting                 | 0: Parameter is displayed in "group mode"  | 0     |  |
|   |       |  | 1: Parameter is displayed in "sequence P mode"                                       |       |  |

► Basic Parameter Group 01

| Group | No.  | Name  | Setting Range                                       | Default  | User Setting |
|-------|------|---|---|----------|--------------|
| 01-00 | P.1  | Maximum frequency                             | 0.00~01.02 (P.18) Hz                                | 120.00Hz |              |
| 01-01 | P.2  | Minimum frequency                             | 0~120.00Hz  | 0.00Hz   |              |
| 01-02 | P.18 | High-speed maximum frequency                  | 01.00 (P.1) ~650.00Hz                               | 120.00Hz |              |
| 01-03 | P.3  | Base frequency                                | 50Hz system setting: 0~650.00Hz                     | 50.00Hz  |              |
|       |      |   | 60Hz system setting: 0~650.00Hz                     |          |              |
| 01-04 | P.19 | Base voltage                                  | 0~1000.0V   | 99999    |              |
|       |      |   | 99999: Change according to the input voltage        |          |              |
| 01-05 | P.29 | Acceleration/deceleration curve selection     | 0: Linear acceleration /deceleration curve          | 0        |              |
|       |      |   | 1: S shape acceleration /deceleration curve 1       |          |              |
|       |      |   | 2: S shape acceleration /deceleration curve 2       |          |              |
|       |      |   | 3: S shape acceleration /deceleration curve 3       |          |              |
| 01-06 | P.7  | Acceleration time                             | 0~360.00s/0~3600.0s : 3.7Kw and below               | 5.00s    |              |
| 01-07 | P.8  | Deceleration time                             | 0~360.00s/0~3600.0s : 3.7Kw and below               | 5.00s    |              |
|       |      |   | 0~360.00s/0~3600.0s : 5.5Kw model                   |          |              |
| 01-08 | P.21 | Acceleration/deceleration time increments     | 0: Time increment is 0.01s                          | 0        |              |
|       |      |   | 1: Time increment is 0.1s                           |          |              |
| 01-09 | P.20 | Acceleration/deceleration reference frequency | 50Hz system setting: 1.00~599.00Hz                  | 50.00Hz  |              |
| 01-10 | P.0  | Torque boost                                  | 0~30.0% : 0.75K and under                           | 6.0%     |              |
|       |      |   | 0~30.0% : 1.5K~3.7K                                 |          |              |
| 01-11 | P.13 | Starting frequency                            | 0~60.00Hz   | 0.50Hz   |              |
|       |      |   | 0: For constant torque loads (conveyor belt, etc.)  |          |              |
| 01-12 | P.14 | Load pattern selection                        | 1: For variable torque loads (fans and pumps, etc.) | 0        |              |
|       |      |   | 2, 3: For Lifting loads                             |          |              |
|       |      |   | 4: Multipoint V/F curve                             |          |              |
|       |      |   | 5~13: Special two-point V/F curve                   |          |              |
| 01-13 | P.15 | JOG frequency                                 | 0~650.00Hz  | 5.00Hz   |              |
| 01-14 | P.16 | JOG Acc/ Dec time                             | 0~360.00s/0~3600.0s                                 | 0.50s    |              |
| 01-15 | P.28 | Output frequency filter time                  | 0~31  | 0        |              |
| 01-16 | P.91 | Frequency jump 1A                             | 0~650.00Hz  | 99999    |              |
|       |      |   | 99999: Off  |          |              |
| 01-17 | P.92 | Frequency jump 1B                             | 0~650.00Hz  | 99999    |              |
|       |      |   | 99999: Off  |          |              |
| 01-18 | P.93 | Frequency jump 2A                             | 0~650.00Hz  | 99999    |              |
|       |      |   | 99999: Off  |          |              |
| 01-19 | P.94 | Frequency jump 2B                             | 0~650.00Hz  | 99999    |              |
|       |      |   | 99999: Off  |          |              |
| 01-20 | P.95 | Frequency jump 3A                             | 0~650.00Hz  | 99999    |              |
|       |      |   | 99999: Off  |          |              |
| 01-21 | P.96 | Frequency jump 3B                             | 0~650.00Hz  | 99999    |              |
|       |      |   | 99999: Off  |          |              |
| 01-22 | P.44 | Second acceleration time                      | 0~360.00s/0~3600.0s                                 | 99999    |              |
| 01-23 | P.45 | Second deceleration time                      | 0~360.00s/0~3600.0s                                 | 99999    |              |
| 01-24 | P.46 | Second torque boost                           | 0~30.0%   | 99999    |              |
| 01-25 | P.47 | Second base frequency                         | 0~650.00Hz  | 99999    |              |
| 01-26 | P.98 | Middle frequency 1                            | 0~650.00Hz  | 3.00Hz   |              |
| 01-27 | P.99 | Output voltage 1 of middle frequency          | 0~100.0%  | 10.0%    |              |

|       |       |   |  |            |       |
|-------|-------|---|--|------------|-------|
| 01-28 | P.162 | Middle frequency 2                            | 0~650.00Hz   | 99999: Off | 99999 |
| 01-29 | P.163 | Output voltage 2 of middle frequency          | 0~100.0%   |            | 0.0%  |
| 01-30 | P.164 | Middle frequency 3                            | 0~650.00Hz   | 99999: Off | 99999 |
| 01-31 | P.165 | Output voltage 3 of middle frequency          | 0~100.0%   |            | 0.0%  |
| 01-32 | P.166 | Middle frequency 4                            | 0~650.00Hz   | 99999: Off | 99999 |
| 01-33 | P.167 | Output voltage 4 of middle frequency          | 0~100.0%   |            | 0.0%  |
| 01-34 | P.168 | Middle frequency 5                            | 0~650.00Hz   | 99999: Off | 99999 |
| 01-35 | P.169 | Output voltage 5 of middle frequency          | 0~100.0%   |            | 0.0%  |
| 01-36 | P.255 | S curve time at the beginning of acceleration | 0~25.00s/0~250.0s                                  |            | 0.20s |
| 01-37 | P.256 | S curve time at the end of acceleration       | 0~25.00s/0~250.0s                                  | 99999: Off | 99999 |
| 01-38 | P.257 | S curve time at the beginning of deceleration | 0~25.00s/0~250.0s                                  | 99999: Off | 99999 |
| 01-39 | P.258 | S curve time at the end of deceleration       | 0~25.00s/0~250.0s                                  | 99999: Off | 99999 |
| 01-40 | P.219 | Remote function acc/dec time selection        | 0: Use default acc/dec time (same as regular mode) | 0          |       |
|       |       |   | 1: Use second acc/dec time                         |            |       |

► Analog Input and Output Parameter Group 02

| Group | No.   | Name   | Setting Range  | Default         | User Setting |
|-------|-------|--|--|-----------------|--------------|
| 02-06 | P.185 | Proportional linkage gain  | 0~100%   | 0%              |              |
| 02-07 | P.240 | Auxiliary frequency  | 0: Off   | 0               |              |
|       |       |  | 2: Output frequency = basic frequency + auxiliary frequency (given by terminal 3-5)  |                 |              |
|       |       |  | 4: Output frequency = basic frequency - auxiliary frequency (given by terminal 3-5)  |                 |              |
|       |       |  | 6: Output frequency = proportional linkage signal (given by terminal 3-5)            |                 |              |
| 02-10 | P.60  | Terminal 3-5 filter time   | 0~2000ms   | 31ms            |              |
| 02-20 | P.17  | Terminal 3-5 signal range selection  | 0: Signal sampling range from 4~20mA.  | 1               |              |
|       |       |  | 1: Signal sampling range from 0~10V.   |                 |              |
|       |       |  | 2: Signal sampling range from 0~5V.  |                 |              |
| 02-21 | P.39  | Terminal 3-5 maximum operation frequency                                   | 50 Hz system: 1.00~599.00Hz  | 50.00Hz         |              |
|       |       |  | 60 Hz system: 1.00~599.00Hz  |                 |              |
| 02-24 | P.184 | Terminal 3-5 disconnect selection  | 0: Off   | 0               |              |
|       |       |  | 1: Inverter decelerates to 0Hz, multi-function digital output terminal set off alarm |                 |              |
|       |       |  | 2: Inverter stops immediately, and keypad displays "AEr" alarm                       |                 |              |
| 02-25 | P.198 | Terminal 3-5 minimum input current/ voltage                                | 0~20.00 mA/V   | 0.00V           |              |
|       |       |  | 0~20.00 mA/V   |                 |              |
|       |       |  | 0~20.00 mA/V   |                 |              |
| 02-26 | P.199 | Terminal 3-5 maximum input current/ voltage                                | 0~20.00 mA/V   | 10.00V          |              |
| 02-27 | P.196 | Percentage corresponds to terminal 3-5 minimum input current/ voltage      | 0~100.0%   | 0.0%            |              |
| 02-28 | P.197 | Percentage corresponds to terminal 3-5 maximum input current/ voltage      | 0~100.0%   | 100.0%          |              |
| 02-52 | P.56  | Inverter rated current display level                                       | 0~500.00A  | According to kw |              |
| 02-61 | P.141 | Polarity of percentage corresponds to terminal 3-5 current/ voltage signal | 0~11   | 0               |              |

► Digital Input/ Output Parameter Group 03

| Group | No.  | Name                        | Setting Range  | Default | User Setting |
|-------|------|-----------------------------|--|---------|--------------|
| 03-00 | P.83 | Terminal STF input function | 0: STF(Inverter runs forward)  | 0       |              |
|       |      |                             | 1: STR(Inverter runs reverse)  |         |              |
|       |      |                             | 2: RL(Multi-speed low speed)   |         |              |
|       |      |                             | 3: RM(Multi-speed medium speed)  |         |              |
|       |      |                             | 4: RH(Multi-speed high speed)  |         |              |
|       |      |                             | 5: Reserved  |         |              |
| 03-00 | P.83 | Terminal STF input function | 6: External thermal relay actuate  | 0       |              |
|       |      |                             | 7: MRS(Stops inverter output immediately)  |         |              |
|       |      |                             | 8: RT(Inverter second function)  |         |              |
|       |      |                             | 9: EXJ(External JOG)   |         |              |
|       |      |                             | 10: STF+EXJ  |         |              |
|       |      |                             | 11: STR+EXJ  |         |              |
|       |      |                             | 12: STF+RT   |         |              |
|       |      |                             | 13: STR+RT   |         |              |
|       |      |                             | 14: STF+RL   |         |              |
|       |      |                             | 15: STR+RL   |         |              |
|       |      |                             | 16: STF+RM   |         |              |
|       |      |                             | 17: STR+RM   |         |              |
|       |      |                             | 18: STF+RH   |         |              |
|       |      |                             | 19: STR+RH   |         |              |
|       |      |                             | 20: STF+RL+RM  |         |              |
|       |      |                             | 21: STR+RL+RM  |         |              |
|       |      |                             | 22: STF+RT+RL  |         |              |
|       |      |                             | 23: STR+RT+RL  |         |              |
|       |      |                             | 24: STF+RT+RM  |         |              |
|       |      |                             | 25: STR+RT+RM  |         |              |
|       |      |                             | 26: STF+RT+RL+RM   |         |              |
|       |      |                             | 27: STR+RT+RL+RM   |         |              |
|       |      |                             | 28: RUN(Inverter runs forward)   |         |              |
|       |      |                             | 29: STF/STR(use with RUN signal, when ON, motor runs reverse ; when OFF, motor runs forward) |         |              |
|       |      |                             | 30: RES(External reset function)   |         |              |
|       |      |                             | 31: STOP(Use as three line control with RUN signal and STF-STR signal)                       |         |              |
|       |      |                             | 32: REX(Extend multi-speed to 16 levels)   |         |              |
|       |      |                             | 33: PO(In "external mode", run programmed operation)   |         |              |
|       |      |                             | 34: RES_E (External reset, valid only when alarm.)   |         |              |
|       |      |                             | 35: MPO (In "external mode" run manual cycle operation.)                                     |         |              |
|       |      |                             | 36: TRI(Triangle wave function)  |         |              |
|       |      |                             | 37: Reserved   |         |              |
|       |      |                             | 38: Reserved   |         |              |
|       |      |                             | 39: STF/STR +STOP (Use with RUN signal, when ON, motor runs                                  |         |              |

|       |       |   |   |  |        |
|-------|-------|---|---|--|--------|
|       |       |   | reverse, when OFF, motor stops then runs forward.)  |  |        |
|       |       |   | 40: P_MRS (Stops inverter output immediately by pulse signal input)   |  |        |
|       |       |   | 41-42: Reserved   |  |        |
|       |       |   | 43: RUN_EN (Enable digital input terminal operation)  |  |        |
|       |       |   | 44: PID_OFF (Enable digital input terminal turning off PID)   |  |        |
|       |       |   | 45: Second frequency command source mode  |  |        |
|       |       |   | 46-91:Reserved  |  |        |
|       |       |   | 92: Fire mode command 1 (with run command)  |  |        |
|       |       |   | 93: Fire mode command 2 (without run command)   |  |        |
| 03-01 | P.84  | Terminal STR input function                     | Same as 03-00   |  | 1      |
| 03-03 | P.80  | Terminal M0 input function                      | Same as 03-00   |  | 2      |
| 03-04 | P.81  | Terminal M1 input function                      | Same as 03-00   |  | 3      |
| 03-11 | P.85  | Terminal A-C output function                    | 0: RUN(Output when inverter running)<br>1: SU(Output when reach target frequency)<br>2: FU(Output when reach 03-21 03-22 value )<br>3: OL(Output when overload)<br>4: OMD(Output when output current is zero)<br>5: ALARM(Output when alarm)<br>6: PO1(Output when in program operation step)<br>7: PO2(Output when in program operation cycle)<br>8: PO3(Output when in program operation pause)<br>9: Reserved<br>10: Reserved<br>11: OMD1(Output when output current is zero 1)<br>12: OL2(Output when over torque)<br>13~16: Reserved<br>17: RY(Output when inverter is powered on and no alarm)<br>18: Output when it's time for maintenance<br>41: PID feedback line break (AErr) alarm<br>42: Fire mode indication |  | 5      |
| 03-14 | P.87  | Digital input logic                             | 0~15  |  | 0      |
| 03-15 | P.88  | Digital output logic                            | 0: Terminal A-C output positive logic<br>2: Terminal A-C output negative logic  |  | 0      |
| 03-16 | P.120 | Output signal delay time                        | 0~3600.0s   |  | 0.0s   |
| 03-17 | P.157 | Digital input terminal filter time              | 0~2000  |  | 4      |
| 03-18 | P.158 | Digital input terminal enable when power on     | 0: When power on digital terminals work directly<br>1: When power on digital terminals work after switch off then on  |  | 0      |
| 03-20 | P.41  | Output frequency detection sensitivity          | 0~100.0%  |  | 10.0%  |
| 03-21 | P.42  | Output frequency detection for forward rotation | 0~650.00Hz  |  | 6.00Hz |
| 03-22 | P.43  | Output frequency detection for reverse rotation | 0~650.00Hz<br>99999: Same as the setting of 03-21(P.42)   |  | 99999  |
| 03-23 | P.62  | Zero current detection level                    | 0~200.0%<br>99999: Off  |  | 5.0%   |
| 03-24 | P.63  | Zero current detection time                     | 0.05~100.00s<br>99999: Off  |  | 0.50s  |

> Multi-speed Parameter Group 04

| Group | No.   | Name  | Setting Range  | Default | User Setting |
|-------|-------|---|--|---------|--------------|
| 04-00 | P.4   | Speed 1 (high speed)  | 0~650.00Hz   | 60.00Hz |              |
| 04-01 | P.5   | Speed 2 (medium speed)  | 0~650.00Hz   | 30.00Hz |              |
| 04-02 | P.6   | Speed 3 (low speed)   | 0~650.00Hz   | 10.00Hz |              |
| 04-03 | P.24  | Speed 4   | 0~650.00Hz<br>99999: Off   | 99999   |              |
| 04-04 | P.25  | Speed 5   | Same as 04-03(P.24)  | 99999   |              |
| 04-05 | P.26  | Speed 6   | Same as 04-03(P.24)  | 99999   |              |
| 04-06 | P.27  | Speed 7   | Same as 04-03(P.24)  | 99999   |              |
| 04-07 | P.142 | Speed 8   | Same as 04-03(P.24)  | 0.00Hz  |              |
| 04-08 | P.143 | Speed 9   | Same as 04-03(P.24)  | 99999   |              |
| 04-09 | P.144 | Speed 10  | Same as 04-03(P.24)  | 99999   |              |
| 04-10 | P.145 | Speed 11  | Same as 04-03(P.24)  | 99999   |              |
| 04-11 | P.146 | Speed 12  | Same as 04-03(P.24)  | 99999   |              |
| 04-12 | P.147 | Speed 13  | Same as 04-03(P.24)  | 99999   |              |
| 04-13 | P.148 | Speed 14  | Same as 04-03(P.24)  | 99999   |              |
| 04-14 | P.149 | Speed 15  | Same as 04-03(P.24)  | 99999   |              |
| 04-15 | P.100 | Programmed operation minute / second selection                          | 0: Select minute as the time increment.<br>1: Select second as the time increment.   | 1       |              |
| 04-16 | P.121 | Run direction in each section   | 0~255  | 0       |              |
| 04-17 | P.122 | Programmed operation cycle selection                                    | 0:Off<br>1~8: Start cycle from the set section.  | 0       |              |
| 04-18 | P.123 | Programmed operation acceleration / deceleration time setting selection | 0:Acceleration time is 01-06(P.7), deceleration time is 01-07(P.8).<br>1:Acceleration and deceleration time is set by 04-35(P.111) ~ 04-42(P.118). | 0       |              |
| 04-19 | P.131 | Programmed operation mode speed 1                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-20 | P.132 | Programmed operation mode speed 2                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-21 | P.133 | Programmed operation mode speed 3                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-22 | P.134 | Programmed operation mode speed 4                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-23 | P.135 | Programmed operation mode speed 5                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-24 | P.136 | Programmed operation mode speed 6                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-25 | P.137 | Programmed operation mode speed 7                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-26 | P.138 | Programmed operation mode speed 8                                       | 0~650.00Hz   | 0.00Hz  |              |
| 04-27 | P.101 | Programmed operation mode speed 1 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-28 | P.102 | Programmed operation mode speed 2 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-29 | P.103 | Programmed operation mode speed 3 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-30 | P.104 | Programmed operation mode speed 4 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-31 | P.105 | Programmed operation mode speed 5 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-32 | P.106 | Programmed operation mode speed 6 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-33 | P.107 | Programmed operation mode speed 7 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-34 | P.108 | Programmed operation mode speed 8 operating time                        | 0~6000.0s  | 0.0s    |              |
| 04-35 | P.111 | Programmed operation mode speed 1 Acc/Dec time                          | 0~600.00s/0~6000.0s  | 0.00s   |              |
| 04-36 | P.112 | Programmed operation mode speed 2 Acc/Dec time                          | 0~600.00s/0~6000.0s  | 0.00s   |              |
| 04-37 | P.113 | Programmed operation mode speed   | 0~600.00s/0~6000.0s  | 0.00s   |              |

|       |       |                |  |                     |       |  |
|-------|-------|----------------|--|---------------------|-------|--|
| 04-38 | P.114 | 3 Acc/Dec time | Programmed operation mode speed 4 Acc/Dec time | 0~600.00s/0~6000.0s | 0.00s |  |
| 04-39 | P.115 | 4 Acc/Dec time | Programmed operation mode speed 5 Acc/Dec time | 0~600.00s/0~6000.0s | 0.00s |  |
| 04-40 | P.116 | 5 Acc/Dec time | Programmed operation mode speed 6 Acc/Dec time | 0~600.00s/0~6000.0s | 0.00s |  |
| 04-41 | P.117 | 6 Acc/Dec time | Programmed operation mode speed 7 Acc/Dec time | 0~600.00s/0~6000.0s | 0.00s |  |
| 04-42 | P.118 | 7 Acc/Dec time | Programmed operation mode speed 8 Acc/Dec time | 0~600.00s/0~6000.0s | 0.00s |  |

> Motor Parameter Group 05

| Group | No.   | Name                                       | Setting Range  | Default                | User Setting |
|-------|-------|--|--|------------------------|--------------|
| 05-00 | P.301 | Motor specifications automatic measurement | 0: Off<br>1: Induction motor specifications automatic measurement (Run motor to measure)<br>2: Induction motor specifications automatic measurement (Don't run motor to measure)<br>3: Induction motor specifications automatic measurement (Measure when operating) | 0                      |              |
| 05-01 | P.302 | Motor rated power                          | 0~160.00kW   | 0.00kW                 |              |
| 05-02 | P.303 | Motor poles                                | 0~48   | 4                      |              |
| 05-03 | P.304 | Motor rated voltage                        | 0~510V   | 380V/440V<br>220V      |              |
| 05-04 | P.305 | Motor rated frequency                      | 50Hz system: 0~650.00Hz<br>60Hz system: 0~650.00Hz   | 50.00Hz<br>60.00Hz     |              |
| 05-05 | P.306 | Motor rated current                        | 0~500.0A   | According to kw        |              |
| 05-06 | P.307 | Motor rated rotation speed                 | 50Hz system: 0~9998r/min<br>60Hz system: 0~9998r/min   | 1410r/min<br>1710r/min |              |
| 05-07 | P.308 | Motor excitation current                   | 0~500.0A   | According to kw        |              |
| 05-08 | P.309 | IM motor stator resistance                 | 0~99.98Ω   | According to kw        |              |

> Protection Parameter Group 06

| Group | No.   | Name  | Setting Range  | Default            | User Setting |
|-------|-------|---|--|--------------------|--------------|
| 06-00 | P.9   | Electronic thermal relay capacity                       | 0~500.00A  | 0.00A              |              |
| 06-01 | P.22  | Stall prevention operation level                        | 0~250.0%   | 150.0%             |              |
| 06-02 | P.23  | Stall prevention operation level correction factor      | 0~200.0%<br>99999: Stall prevention operation level is the setting value of 06-01(P.22).   | 99999              |              |
| 06-03 | P.66  | Stall prevention operation reduction starting frequency | 50Hz system: 0~650.00Hz<br>60Hz system: 0~650.00Hz   | 50.00Hz<br>60.00Hz |              |
| 06-05 | P.30  | Regenerative brake selection                            | 0: Brake duty is fixed at 3%, parameter 06-06(P.70) will be off.<br>1: Brake duty is 06-06(P.70) value.  | 0                  |              |
| 06-06 | P.70  | Special regenerative brake duty                         | 0~100.0%   | 0.0%               |              |
| 06-08 | P.155 | Over torque detection level                             | 0~200.0%   | 0.0%               |              |
| 06-09 | P.156 | Over torque detection time                              | 0~60.0s  | 1.0s               |              |
| 06-10 | P.260 | Action when detect over torque                          | 0: OL2 alarm will not be reported after over torque detection, and inverter keeps running.<br>1: OL2 alarm will be reported after over torque detection, and inverter stops.   | 1                  |              |
| 06-12 | P.245 | Cooling fan working mode                                | 0: When running turn on the fan, after stop for 30 seconds turn off the fan.<br>1: When power on turn on the fan, after power off turn off the fan.<br>2: When running and the heat sink temperature exceeds 60°C turn on the fan, under 40°C turn off the fan.<br>3: When the heat sink temperature exceeds 60°C turn on the fan, under 40°C turn off the fan.  | 1                  |              |
| 06-13 | P.281 | Input phase loss protection                             | 0: Off<br>1: When input phase loss, built-in keypad shows iPF alarm and inverter stops   | 0                  |              |
| 06-17 | P.261 | Maintenance alarm function                              | 0: Off<br>1~9998day: Used to set the time for maintenance alarm output signal  | 0                  |              |
| 06-18 | P.280 | Short circuit to ground protection function when start  | 0: Off<br>1: Detect short circuit to ground when inverter start  | 0                  |              |
| 06-19 | P.282 | GF detection level when operating                       | 0~100%   | 50%                |              |
| 06-27 | P.292 | Total inverter operation time (minutes)                 | 0~1439 min   | 0 min              |              |
| 06-28 | P.293 | Total inverter operation time (days)                    | 0~9999 day   | 0 day              |              |
| 06-29 | P.296 | Total inverter power on time (minutes)                  | 0~1439 min   | 0 min              |              |
| 06-30 | P.297 | Total inverter power on time (days)                     | 0~9999 day   | 0 day              |              |
| 06-40 | P.288 | Alarm record code query                                 | Choose 0~12 recorded alarm   | 0                  |              |
| 06-41 | P.289 | Alarm record code display                               | Read only  | Read only          |              |
| 06-42 | P.290 | Alarm record message query                              | Choose 0~10 recorded alarm   | 0                  |              |
| 06-43 | P.291 | Alarm record message display                            | Read only  | Read only          |              |
| 06-84 | P.207 | Fire mode   | XXX0:Off (fire mode off (normal mode))<br>XXX1:Forward operation (inverter runs forward in fire mode)<br>XXX2:Reverse operation (inverter runs reverse in fire mode)<br>0XXX:Manual exit fire mode 1 (after the fire mode terminal function is off, manually reset inverter to go to normal mode)<br>1XXX:Auto exit fire mode 1 (after the fire mode terminal function is off, inverter automatically return to normal mode)<br>2XXX: Manual exit fire mode 2 (after the fire mode terminal function is off, The inverter continues to keep running, manually reset inverter to go to normal mode) | 0                  |              |
| 06-85 | P.208 | Fire mode frequency                                     | 0~650.00Hz   | 60.00Hz            |              |
| 06-88 | P.209 | Fire mode cumulate times                                | Read only  | Read only          |              |

> Communication Parameter Group 07

| Group | No.  | Name                                  | Setting Range   | Default | User Setting |
|-------|------|---------------------------------------|---|---------|--------------|
| 07-00 | P.33 | Communication protocol selection      | 0: Modbus protocol<br>1: Proprietary protocol   | 1       |              |
| 07-01 | P.36 | Inverter communication station number | 0~254   | 0       |              |
| 07-02 | P.32 | Serial communication baud rate        | 0: Baud rate:4800bps<br>1: Baud rate:9600bps<br>2: Baud rate:19200bps<br>3: Baud rate:38400bps<br>4: Baud rate:57600bps<br>5: Baud rate:115200bps | 1       |              |
| 07-03 | P.48 | Data length                           | 0: 8bit<br>1: 7bit  | 0       |              |
| 07-04 | P.49 | Stop bit length                       | 0: 1bit<br>1: 2bit  | 0       |              |

|       |       |                                     |   |       |  |
|-------|-------|-------------------------------------|---|-------|--|
| 07-05 | P.50  | Parity check selection              | 0: No parity check<br>1: Odd<br>2: Even   | 0     |  |
| 07-06 | P.51  | CR/LF selection                     | 1: CR only<br>2: Both CR and LF   | 1     |  |
| 07-07 | P.154 | Modbus communication format         | 0: 1, 7, N, 2 (Modbus, ASCII)<br>1: 1, 7, E, 1 (Modbus, ASCII)<br>2: 1, 7, O, 1 (Modbus, ASCII)<br>3: 1, 8, N, 2 (Modbus, RTU)<br>4: 1, 8, E, 1 (Modbus, RTU)<br>5: 1, 8, O, 1 (Modbus, RTU)<br>6: 1, 8, N, 1 (Modbus, RTU) | 4     |  |
| 07-08 | P.52  | Number of communication retries     | 0~10  | 1     |  |
| 07-09 | P.53  | Communication interval allowed time | 0~999.8s: Checking communication timeout with the set value<br>99999: No timeout check  | 99999 |  |
| 07-10 | P.153 | Communication alarm action          | 0: Alarm and stop freely<br>1: No alarm and continuing to operation   | 0     |  |
| 07-11 | P.34  | EEPROM write-in selection           | 0: When writing parameters in communication mode, write in RAM and EEPROM<br>1: When writing parameters through communication, only write into RAM  | 0     |  |

> PID Parameter Group 08

| Group | No.   | Name   | Setting Range   | Default            | User Setting |
|-------|-------|--|---|--------------------|--------------|
| 08-00 | P.170 | PID function selection                       | 0: Off<br>2:Parameter 08-03(P.225) as target value, terminal 3-5 current/voltage input as feedback source<br>3: The target value is given by the multi-speed, terminal 3-5 current/voltage input as feedback source | 0                  |              |
| 08-01 | P.171 | PID feedback control method                  | 0: Negative feedback control.<br>1: Positive feedback control.  | 0                  |              |
| 08-03 | P.225 | PID target value from keypad                 | 0~08-43 (P.251)   | 20.0%              |              |
| 08-04 | P.172 | Proportional gain                            | 1~100   | 20                 |              |
| 08-05 | P.173 | Integral time                                | 0~100.0s  | 1.0s               |              |
| 08-06 | P.174 | Differential time                            | 0~1000ms  | 0ms                |              |
| 08-07 | P.175 | Abnormal deviation                           | 0~100.0%  | 0.0%               |              |
| 08-08 | P.176 | Abnormal duration time                       | 0~600.0s  | 30.0s              |              |
| 08-09 | P.177 | Abnormal processing mode                     | 0: Stop freely<br>1: Slow down to stop<br>2: Alarm and continue operation   | 0                  |              |
| 08-10 | P.178 | Sleep detection deviation                    | 0~100.0%  | 0.0%               |              |
| 08-11 | P.179 | Sleep detection duration time                | 0~255.0s  | 1.0s               |              |
| 08-12 | P.180 | Wake-up level                                | 0~100.0%  | 90.0%              |              |
| 08-13 | P.181 | Stop level                                   | 0~120.00Hz  | 40.00Hz            |              |
| 08-14 | P.182 | Upper integral limit                         | 50Hz system:0~120.00Hz<br>60Hz system:0~120.00Hz  | 50.00Hz<br>60.00Hz |              |
| 08-15 | P.183 | Deceleration step length when stable         | 0~10.00Hz   | 0.50Hz             |              |
| 08-18 | P.223 | Analog feedback signal bias                  | 0~100.0%  | 0.0%               |              |
| 08-19 | P.224 | Analog feedback signal gain                  | 0~100.0%  | 100.0%             |              |
| 08-43 | P.251 | PID pressure unit (Bar) setting              | 1.0~100.0   | 100.0              |              |
| 08-45 | P.253 | Analog signal feedback loss detection time   | 0.0~600.0s  | 0.0s               |              |
| 08-46 | P.254 | Analog signal feedback loss action selection | 0: Alarm AErr and inverter stop freely<br>1: Slow down to stop then alarm AErr<br>2: Alarm AErr and continue operation  | 0                  |              |

> Application Parameter Group 10

| Group | No.   | Name                                   | Setting Range  | Default | User Setting |
|-------|-------|--|--|---------|--------------|
| 10-00 | P.10  | DC brake operating frequency           | 0~120.00Hz   | 3.00Hz  |              |
| 10-01 | P.11  | DC brake operating time                | 0~60.0s  | 0.5s    |              |
| 10-02 | P.12  | DC brake operating voltage             | 0~30.0%  | 4.0%    |              |
| 10-03 | P.151 | Zero-speed control function selection  | 0: Off<br>1: DC voltage braking  | 0       |              |
| 10-04 | P.152 | Voltage at zero-speed control          | 0~30.0%  | 5.0%    |              |
| 10-05 | P.242 | DC brake before inverter start         | 0: Off<br>1: Before starting operate DC brake first.   | 0       |              |
| 10-06 | P.243 | DC brake time before inverter start    | 0~60.0s  | 0.5s    |              |
| 10-07 | P.244 | DC brake voltage before inverter start | 0~30.0%  | 4.0%    |              |
| 10-08 | P.150 | Restart mode selection                 | X0: No frequency search.<br>X1: Reserved<br>X2: Decrease voltage mode<br>OX: Power on once.<br>1X: Start each time.<br>2X: Only instantaneous stop and restart<br>3X: Only valid when the fire mode is reset   | 0       |              |
| 10-09 | P.57  | Restart idling time                    | 0~30.0s<br>99999: Off  | 99999   |              |
| 10-10 | P.58  | Restart rising time                    | 0~60.0s  | 10.0s   |              |
| 10-11 | P.61  | Remote control function                | 0: Off<br>X1: Remote control function, frequency save in memory<br>X2: Remote control function, frequency won't save<br>X3: Remote control function, frequency won't save, clear frequency setting every time STF/STR "turn off".<br>X4: Remote control function, frequency save in memory every 5s<br>1X:Frequency command range 01-01(P.2)-01-00(P.1), frequency command value from RH, RM setting | 0       |              |
| 10-12 | P.65  | Auto reset function                    | 0: Off<br>1: When over-voltage, inverter will reset.<br>2: When over-current, inverter will reset.<br>3: When either over-voltage or over-current, inverter will reset.<br>4: When any alarm occurs, inverter will reset.  | 0       |              |
| 10-13 | P.67  | Auto reset times                       | 1~10: If the alarm exceeds 10-13(P.67) times, inverter will not reset.   | 0       |              |
| 10-14 | P.68  | Auto reset waiting time                | 0~360.0s   | 6.0s    |              |
| 10-15 | P.69  | Auto reset times count                 | Read only  | 0       |              |
| 10-16 | P.119 | Forward and reverse rotation dead time | 0~3000.0s  | 0.0s    |              |
| 10-17 | P.159 | Energy-saving control function         | 0: Off<br>1: Energy-saving mode.   | 0       |              |
| 10-18 | P.229 | Dwell function selection               | 0: Off<br>1: Backlash compensation function.<br>2: Acceleration and deceleration interrupt waiting function.   | 0       |              |
| 10-19 | P.230 | Dwell frequency at acceleration        | 0~650.00Hz   | 1.00Hz  |              |
| 10-20 | P.231 | Dwell time at acceleration             | 0~360.0s   | 0.5s    |              |
| 10-21 | P.232 | Dwell frequency at deceleration        | 0~650.00Hz   | 1.00Hz  |              |
| 10-22 | P.233 | Dwell time at deceleration             | 0~360.0s   | 0.5s    |              |

|       |       |  |  |              |  |
|-------|-------|--|--|--------------|--|
| 10-23 | P.234 | Triangular wave function selection       | 0: Off.<br>1: If terminal function TR1 is triggered, triangular wave function will on.<br>2: Triangular wave function is on at all time. | 0            |  |
| 10-24 | P.235 | Maximum amplitude                        | 0~25.0%  | 10.0%        |  |
| 10-25 | P.236 | Amplitude compensation at deceleration   | 0~50.0%  | 10.0%        |  |
| 10-26 | P.237 | Amplitude compensation at acceleration   | 0~50.0%  | 10.0%        |  |
| 10-27 | P.238 | Amplitude acceleration time              | 0~360.00s/0~3600.0s  | 10.00s       |  |
| 10-28 | P.239 | Amplitude deceleration time              | 0~360.00s/0~3600.0s  | 10.00s       |  |
| 10-46 | P.268 | Voltage stall level                      | 220V : 155~400V<br>440V : 310~800V   | 380V<br>760V |  |
| 10-55 | P.226 | Reciprocating machine function selection | 0 : Off<br>1 : Turn on reciprocating machine function  | 0            |  |
| 10-56 | P.227 | Reciprocating forward limit time         | 0~3600.0s  | 0.0s         |  |
| 10-57 | P.228 | Reciprocating reverse limit time         | 0~3600.0s  | 0.0s         |  |

Speed control parameter group 11

| Group | No.   | Name  | Setting Range | Default | User Setting |
|-------|-------|---|---------------|---------|--------------|
| 11-00 | P.320 | Slip compensation gain                          | 0~200%        | 85%     |              |
| 11-01 | P.321 | Torque boost filter coefficient                 | 0~2000        | 20      |              |
| 11-02 | P.322 | Cutoff frequency point of current filter time 1 | 0~30.00Hz     | 4.00Hz  |              |
| 11-03 | P.323 | Current filter time 1                           | 0~400.00ms    | 20.00ms |              |
| 11-04 | P.324 | Low frequency current filter time 2             | 0~400.00ms    | 1.00ms  |              |
| 11-05 | P.325 | High frequency current filter time 2            | 0~400.00ms    | 36.00ms |              |

Special Adjustment Parameter Group 13

| Group | No.   | Name  | Setting Range | Default | User Setting |
|-------|-------|---|---------------|---------|--------------|
| 13-00 | P.89  | Slip compensation coefficient               | 0~10          | 0       |              |
| 13-03 | P.286 | High frequency vibration suppression factor | 0~15          | 0       |              |

User Parameter Group 15

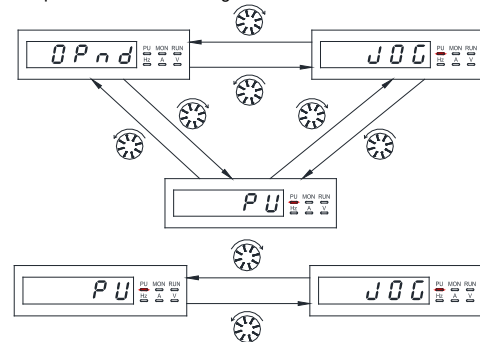
| Group | No.   | Name                         | Setting Range  | Default | User Setting |
|-------|-------|------------------------------|--|---------|--------------|
| 15-00 | P.900 | User registered parameter 1  | P parameter mode:0~399<br>Parameter group mode : 00-00~13-99 | 99999   |              |
| 15-01 | P.901 | User registered parameter 2  |  | 99999   |              |
| 15-02 | P.902 | User registered parameter 3  |  | 99999   |              |
| 15-03 | P.903 | User registered parameter 4  |  | 99999   |              |
| 15-04 | P.904 | User registered parameter 5  |  | 99999   |              |
| 15-05 | P.905 | User registered parameter 6  |  | 99999   |              |
| 15-06 | P.906 | User registered parameter 7  | P parameter mode:0~399<br>Parameter group mode : 00-00~13-99 | 99999   |              |
| 15-07 | P.907 | User registered parameter 8  |  | 99999   |              |
| 15-08 | P.908 | User registered parameter 9  |  | 99999   |              |
| 15-09 | P.909 | User registered parameter 10 |  | 99999   |              |
| 15-10 | P.910 | User registered parameter 11 |  | 99999   |              |
| 15-11 | P.911 | User registered parameter 12 |  | 99999   |              |
| 15-12 | P.912 | User registered parameter 13 |  | 99999   |              |
| 15-13 | P.913 | User registered parameter 14 |  | 99999   |              |
| 15-14 | P.914 | User registered parameter 15 |  | 99999   |              |
| 15-15 | P.915 | User registered parameter 16 |  | 99999   |              |
| 15-16 | P.916 | User registered parameter 17 |  | 99999   |              |
| 15-17 | P.917 | User registered parameter 18 |  | 99999   |              |
| 15-18 | P.918 | User registered parameter 19 |  | 99999   |              |
| 15-19 | P.919 | User registered parameter 20 |  | 99999   |              |

11) Switching Parameter Mode

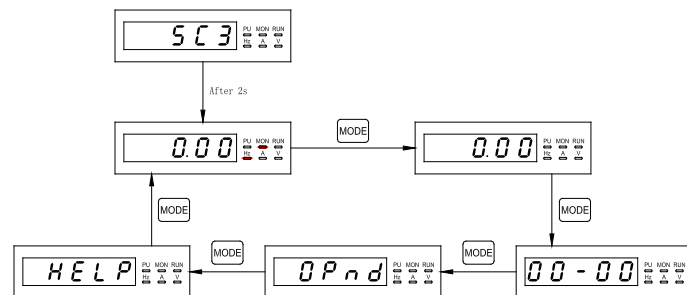
- VFC3 series classify parameters according to functions, and default displayed as "Group Mode"
- If users prefer to display as "P.xxx" mode, please set parameter 00-25 as "1", and parameters will be displayed as "Traditional P Mode".

12) Parameter Setting Flow chart

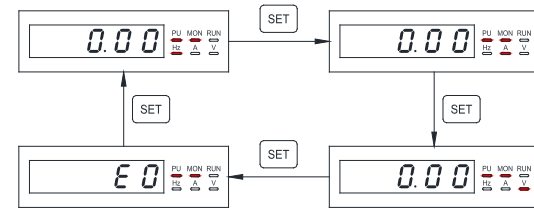
- Operation mode switching flow chart :



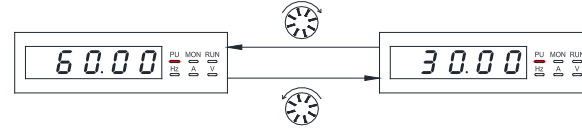
- Work mode switching flow chart :



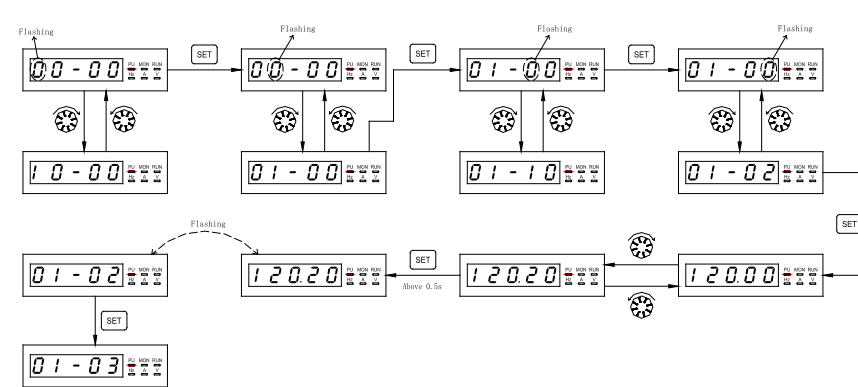
- Monitor mode switching flow chart :



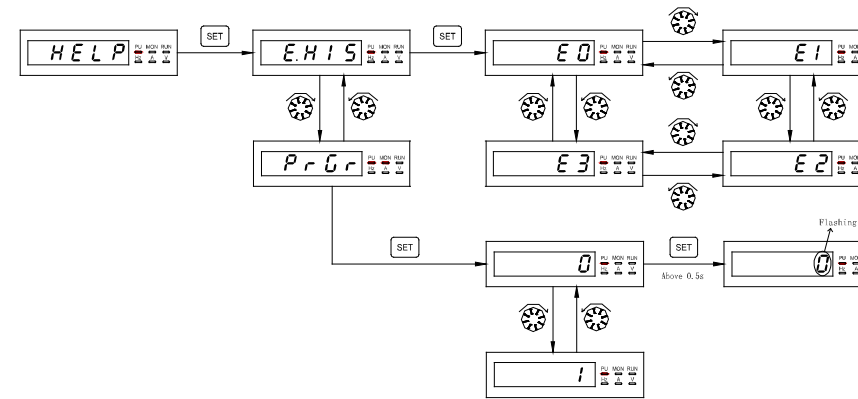
- Frequency setting flow chart :



- Parameter setting flow chart :



- HELP mode flow chart :



13) Others

- To improve our products, the parameters and contents may be modified, please contact the agent or refer to Sit Automation websites (<http://www.sitautomation.it>) to download the latest version.

V1.07 March 2021